

# From DMRG to TNS

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# Graphical Representation

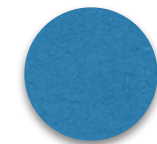
$$A = \begin{bmatrix} A_1 \\ A_2 \\ A_3 \\ \vdots \\ A_N \end{bmatrix}$$

vector

$$B = \begin{bmatrix} B_{11} & \cdots & B_{1n} \\ \vdots & \ddots & \vdots \\ B_{m1} & \cdots & B_{mn} \end{bmatrix}$$

matrix

scalar

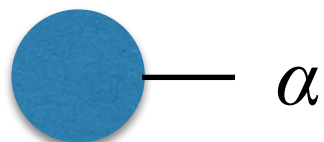


$S$

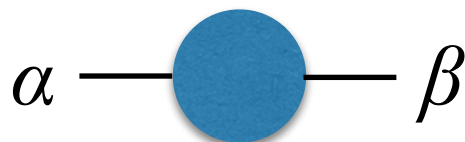
rank-3 tensor

rank- $n$  tensor

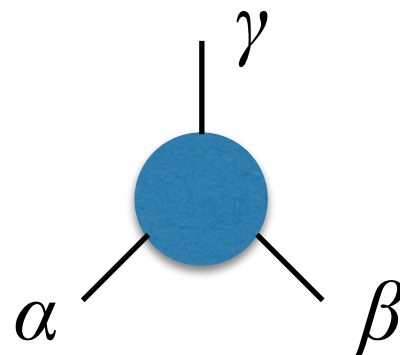
$$A_\alpha$$



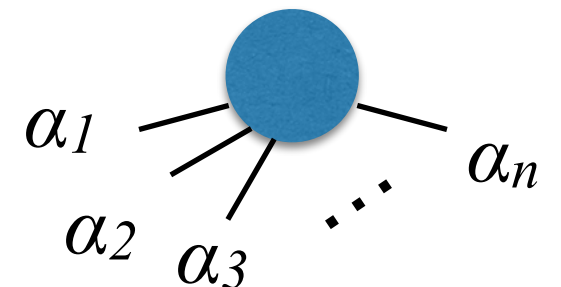
$$B_{\alpha\beta}$$



$$C_{\alpha\beta\gamma}$$

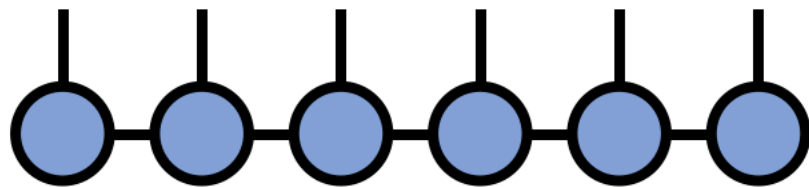


$$T_{\alpha_1 \alpha_2 \alpha_3 \dots \alpha_n}$$

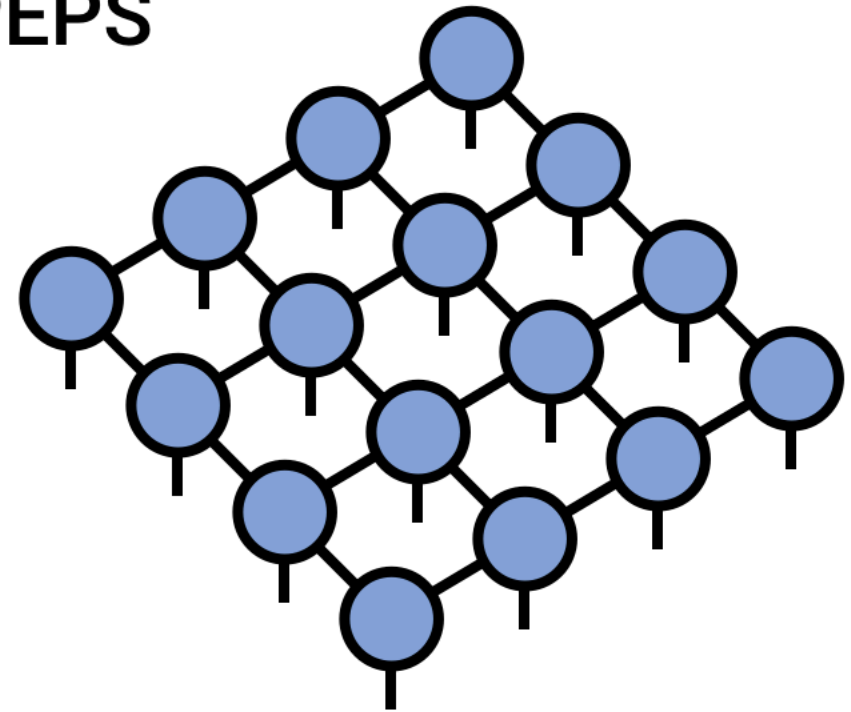


# Tensor Network States

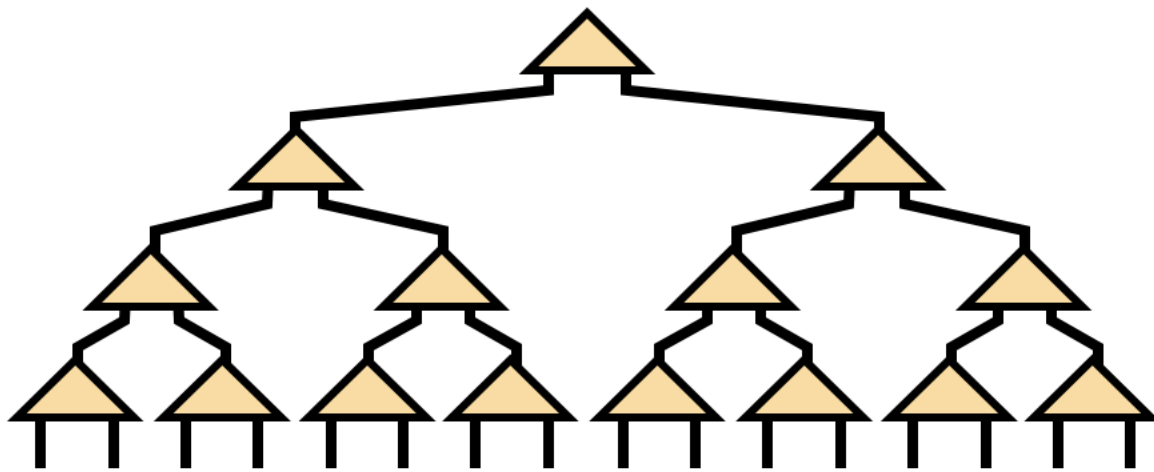
Matrix Product State /  
Tensor Train



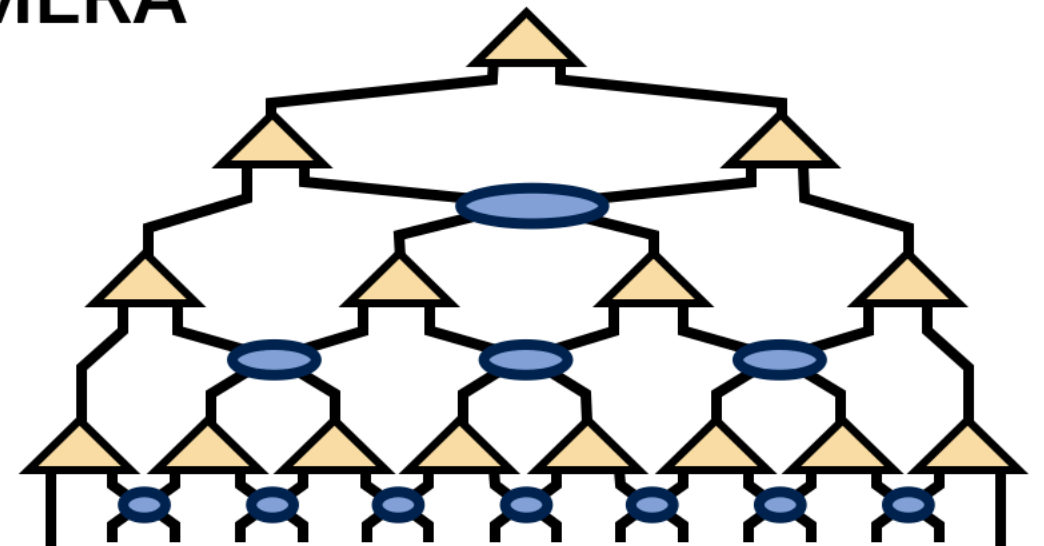
PEPS



Tree Tensor Network /  
Hierarchical Tucker

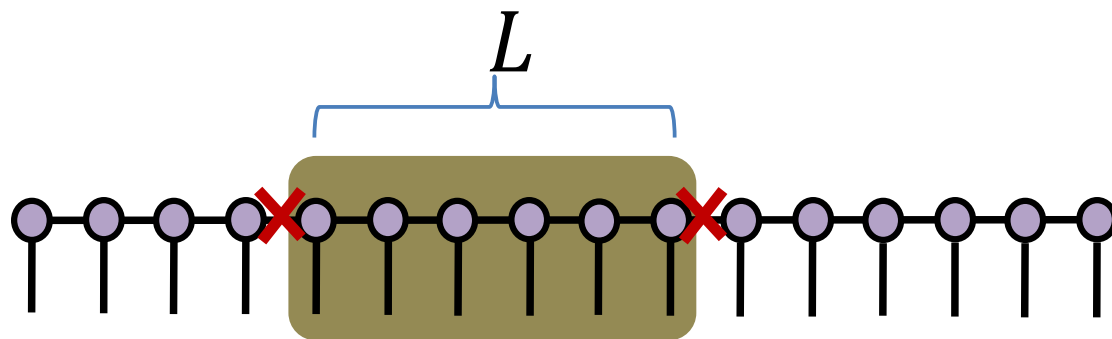


MERA



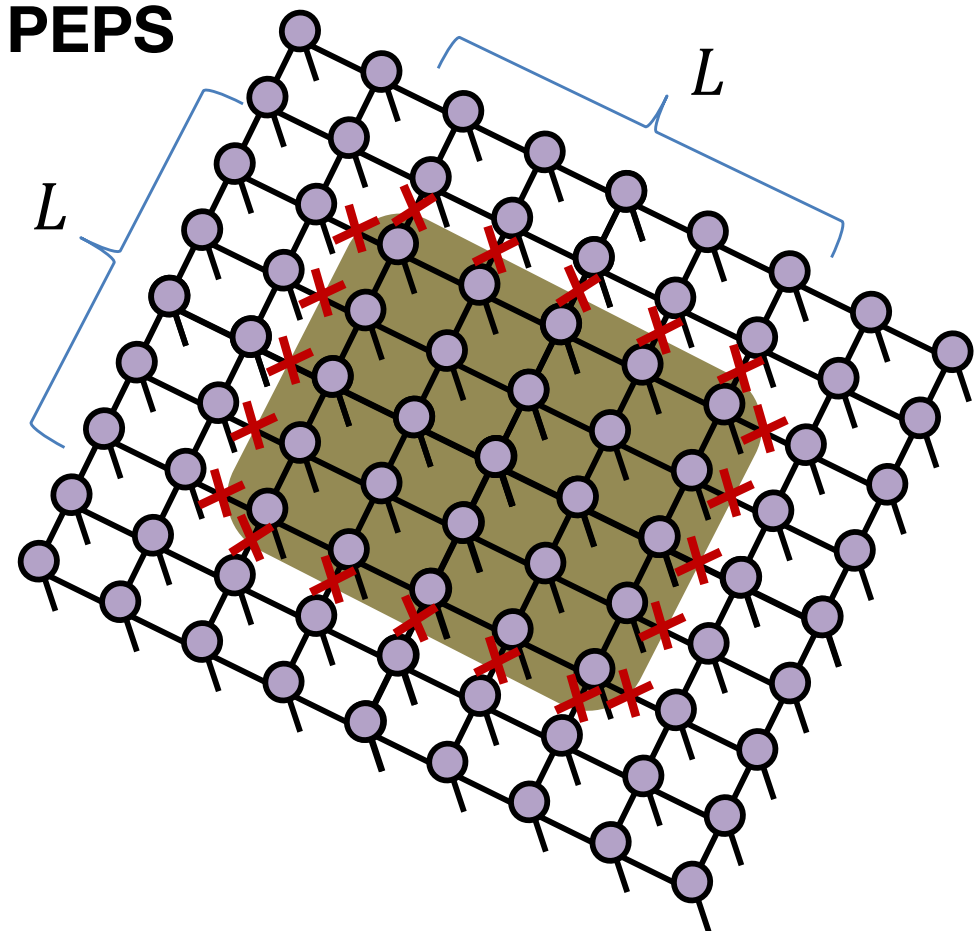
# Entanglement

MPS



$$S_L \sim L^0 \sim \mathbf{const.}$$

PEPS



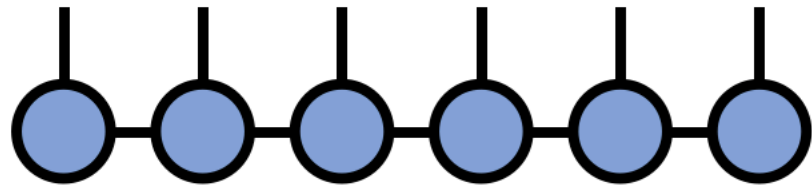
$$S_{L^2} \sim L^1$$

Entanglement area law:  $S_{L^D} \sim L^{D-1}$

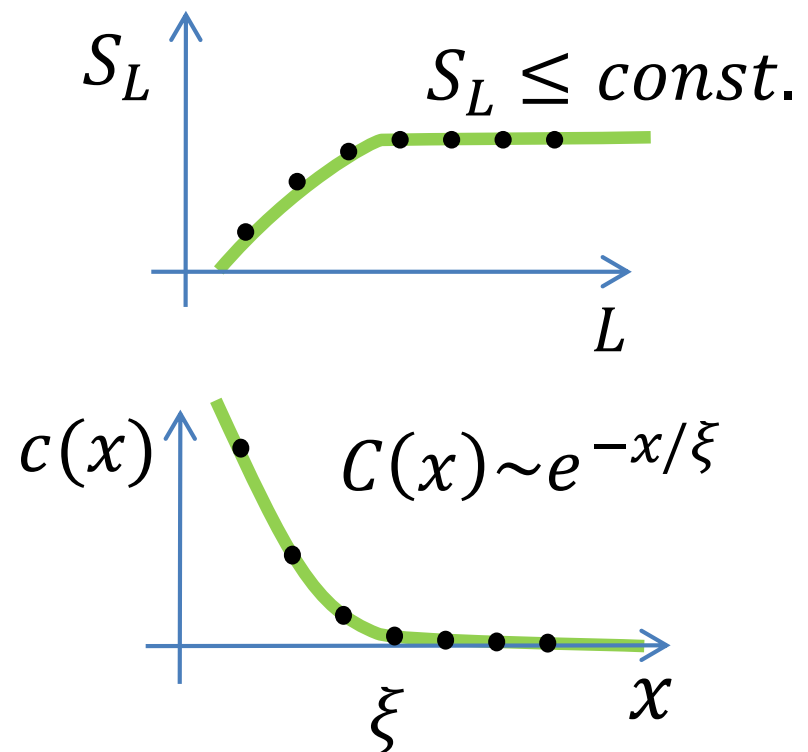


# Tensor Network States

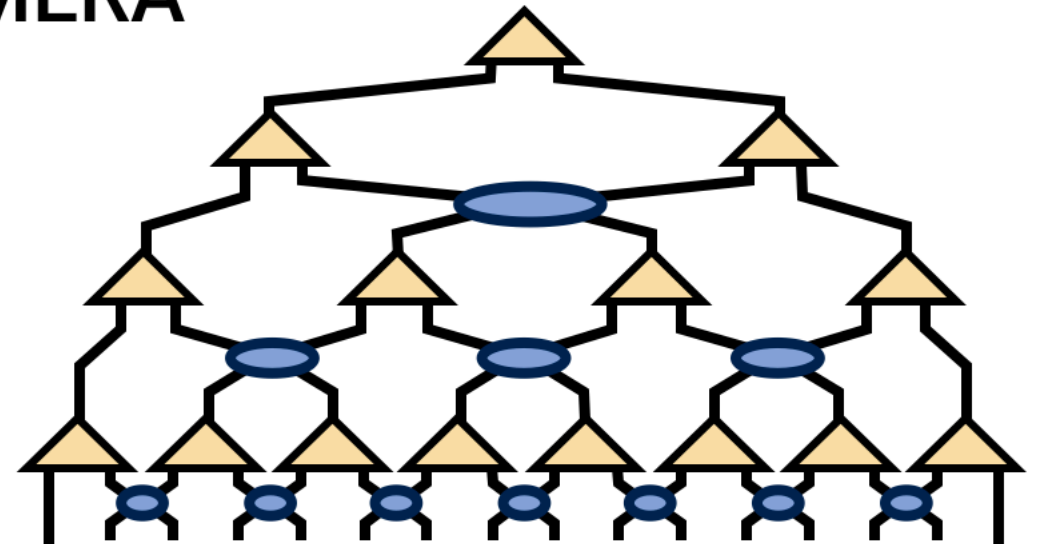
Matrix Product State /  
Tensor Train



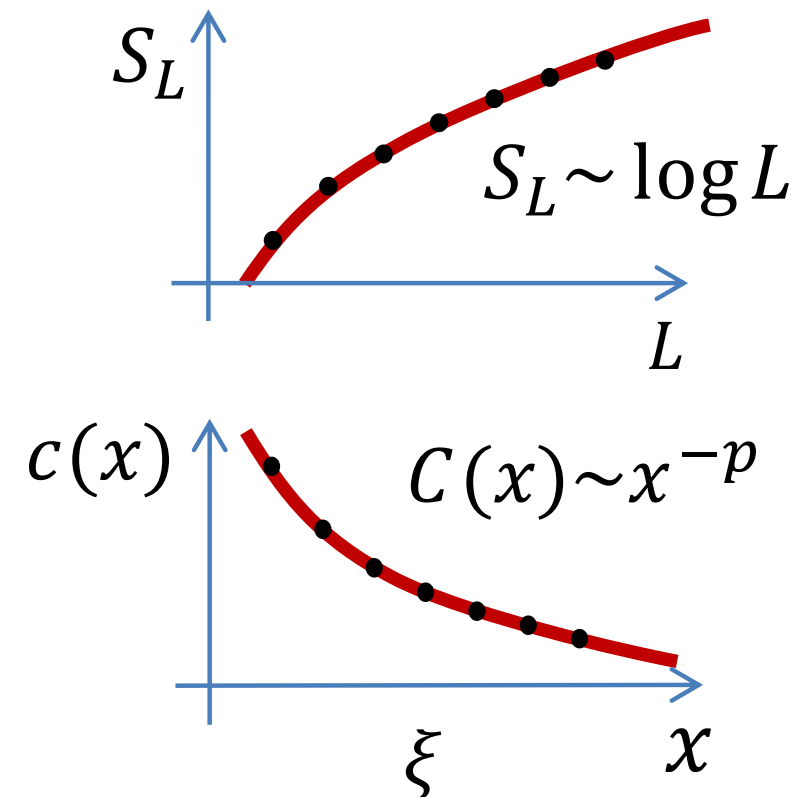
gapped Hamiltonian



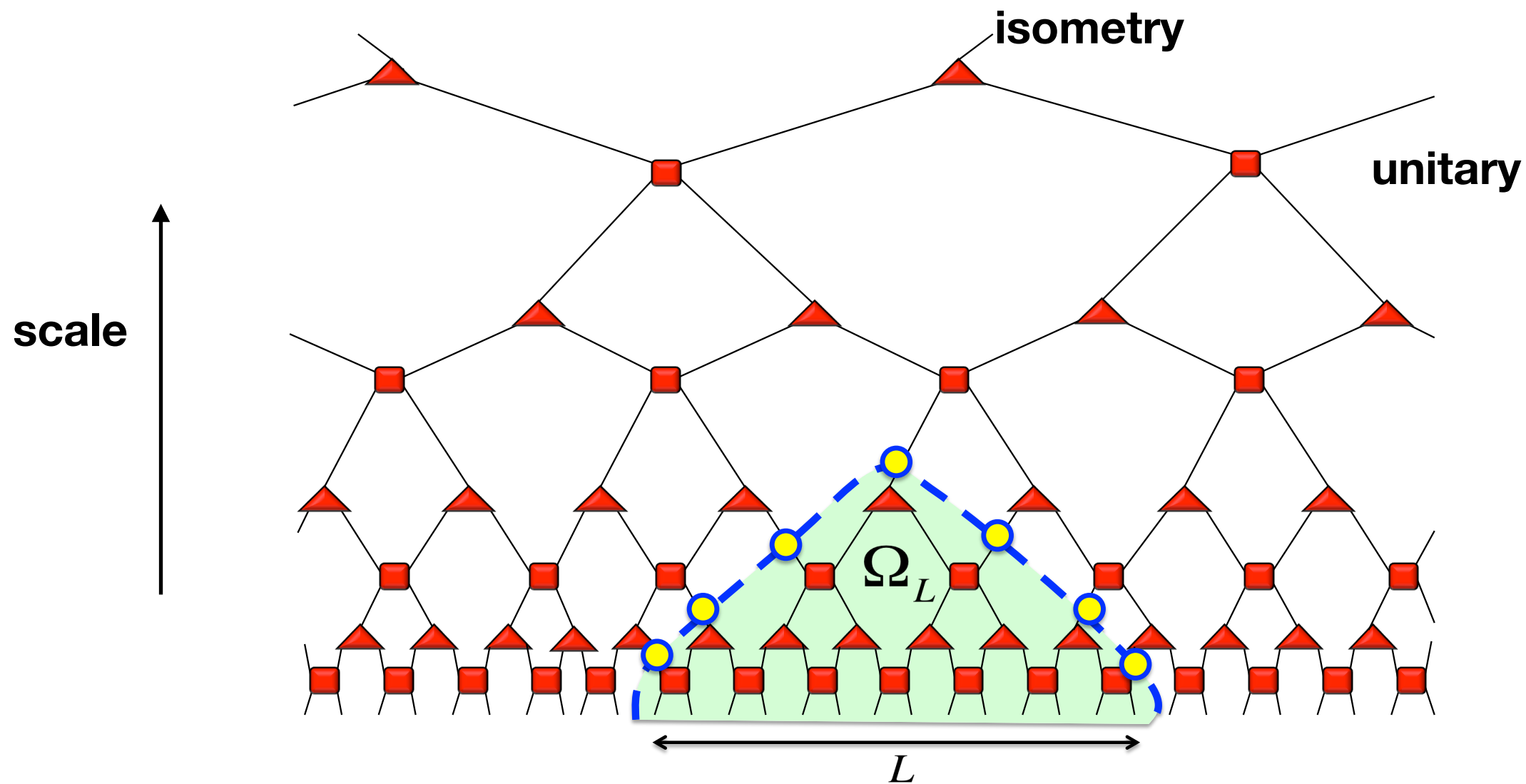
MERA



gapless Hamiltonian



# MERA



$$U \begin{array}{|c|} \hline \text{red square} \\ \hline \end{array} = \begin{array}{|c|} \hline \text{red square} \\ \hline \end{array}$$

$$W \begin{array}{|c|} \hline \text{red triangle} \\ \hline \end{array} = \begin{array}{|c|} \hline \text{red triangle} \\ \hline \end{array}$$

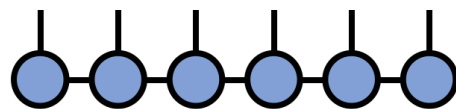
Entanglement Entropy  $\sim$  number of bonds cut

For 1D scale invariant MERA,  $S \sim \log L$

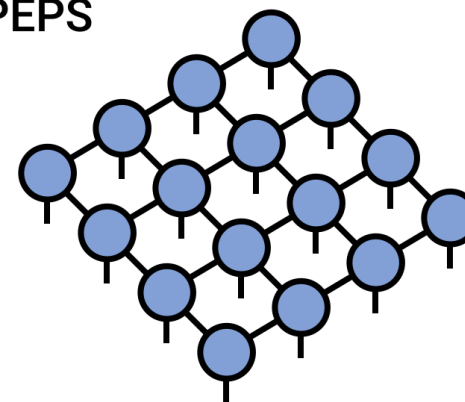
# Entanglement Scaling

	MPS	2d PEPS	TTN	1d MERA	1d bMERA
$S(L)$	$O(1)$	$O(L)$	$O(1)$	$O(\log L)$	$O(L)$
$\langle O \rangle$	exact	approx.	exact	exact	exact
$\xi$	$< \infty$	$\leq \infty$	$< \infty$	$\leq \infty$	$\leq \infty$
Tensors	any	any	any	unit./isom.	unit./isom.
Can. form	obc, $\infty$	no	yes	—	—

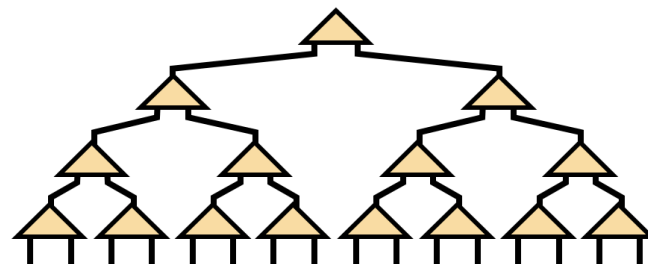
Matrix Product State /  
Tensor Train



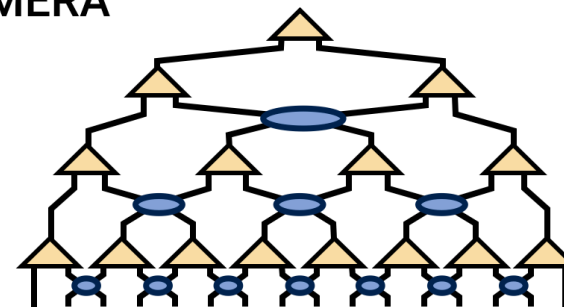
PEPS



Tree Tensor Network /  
Hierarchical Tucker



MERA

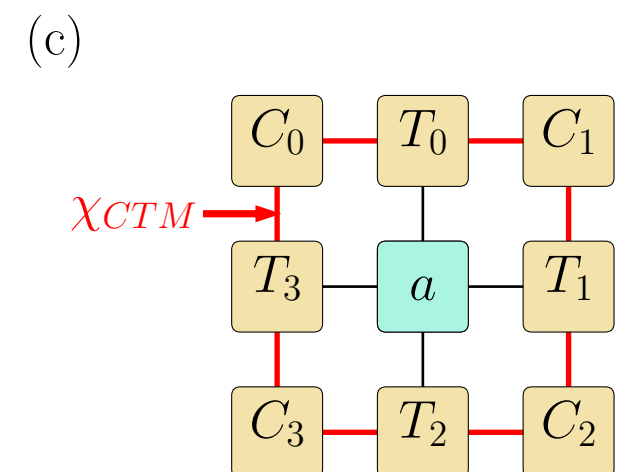
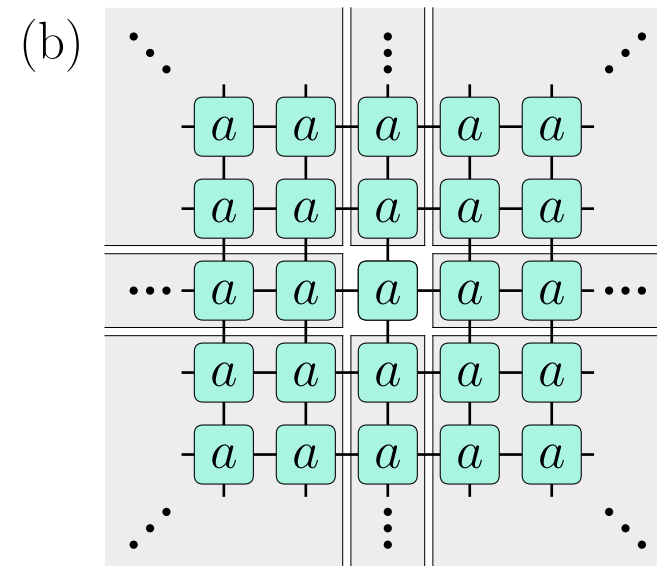
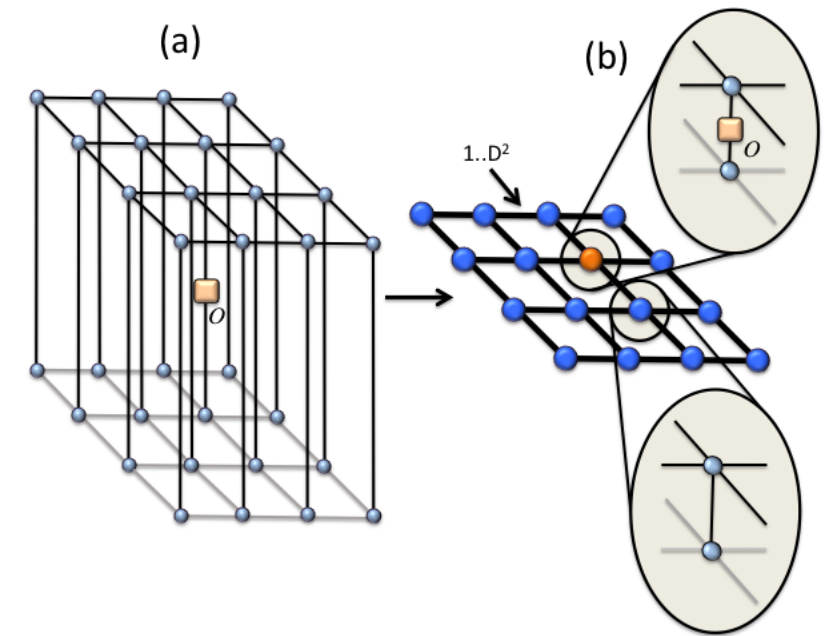


# Algorithms

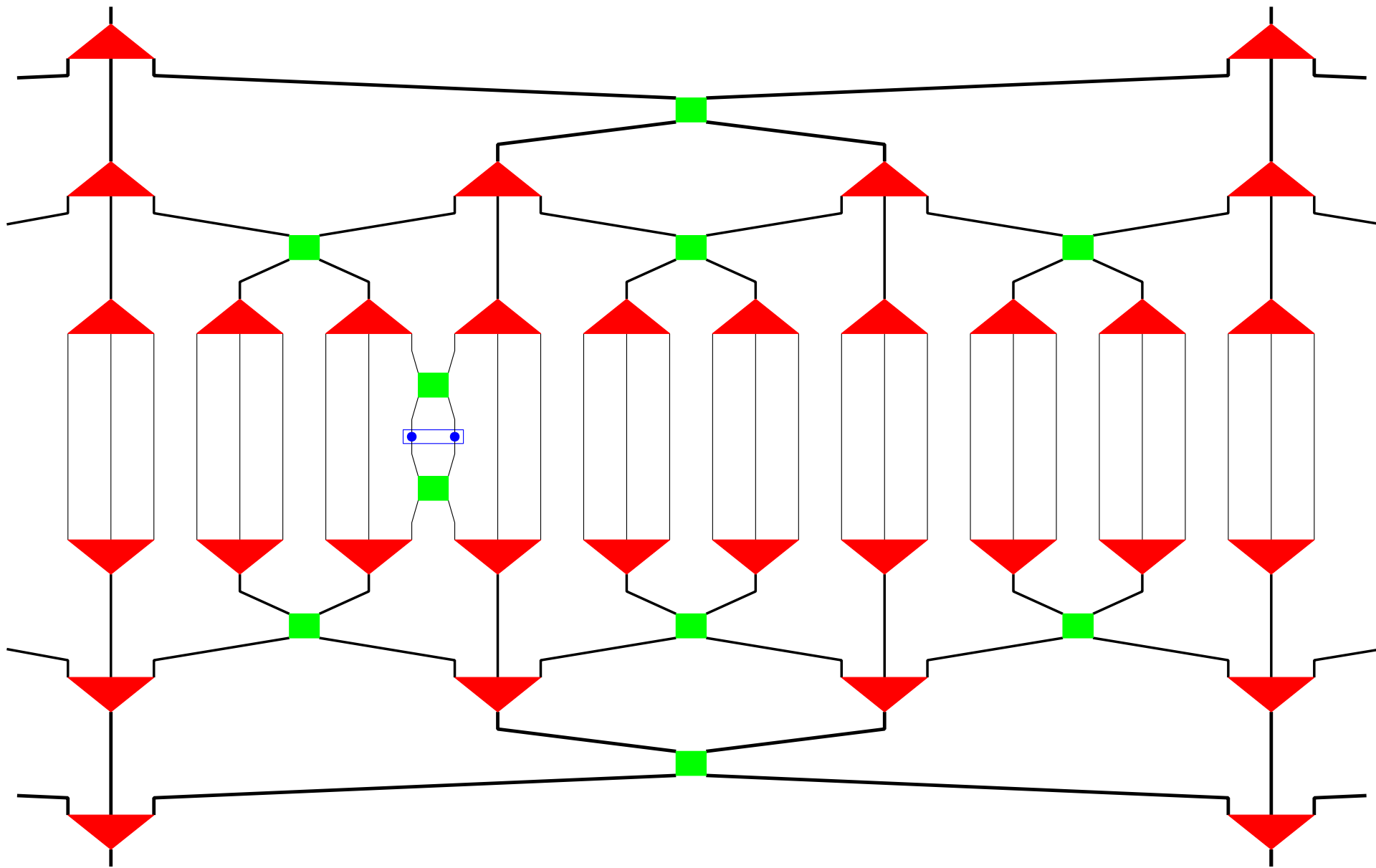
- Finding ground state wave function  $|\psi_g\rangle$
- Imaginary time evolution/ Simple update:  
consider only local environment (Fast, less accurate)
- Variational update/ Full update:  
consider the global environment (Slow, more accurate)

# Algorithms

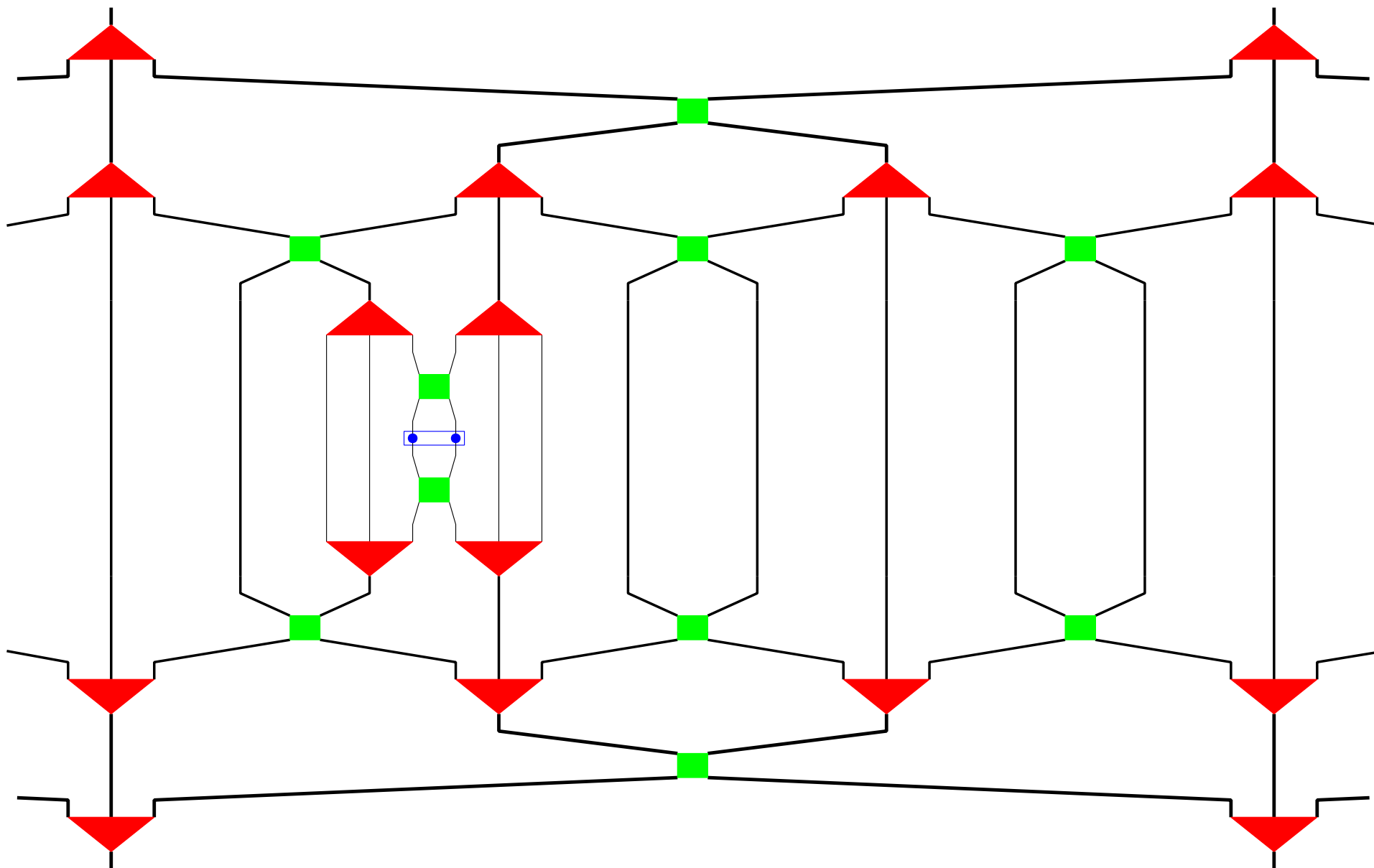
- Expectation value  $\langle \psi_g | O | \psi_g \rangle$
- Finite PEPS: boundary MPS
- Infinite PEPS: Corner Transfer Matrix, boundary MPS, channel method
- MERA: exact contraction



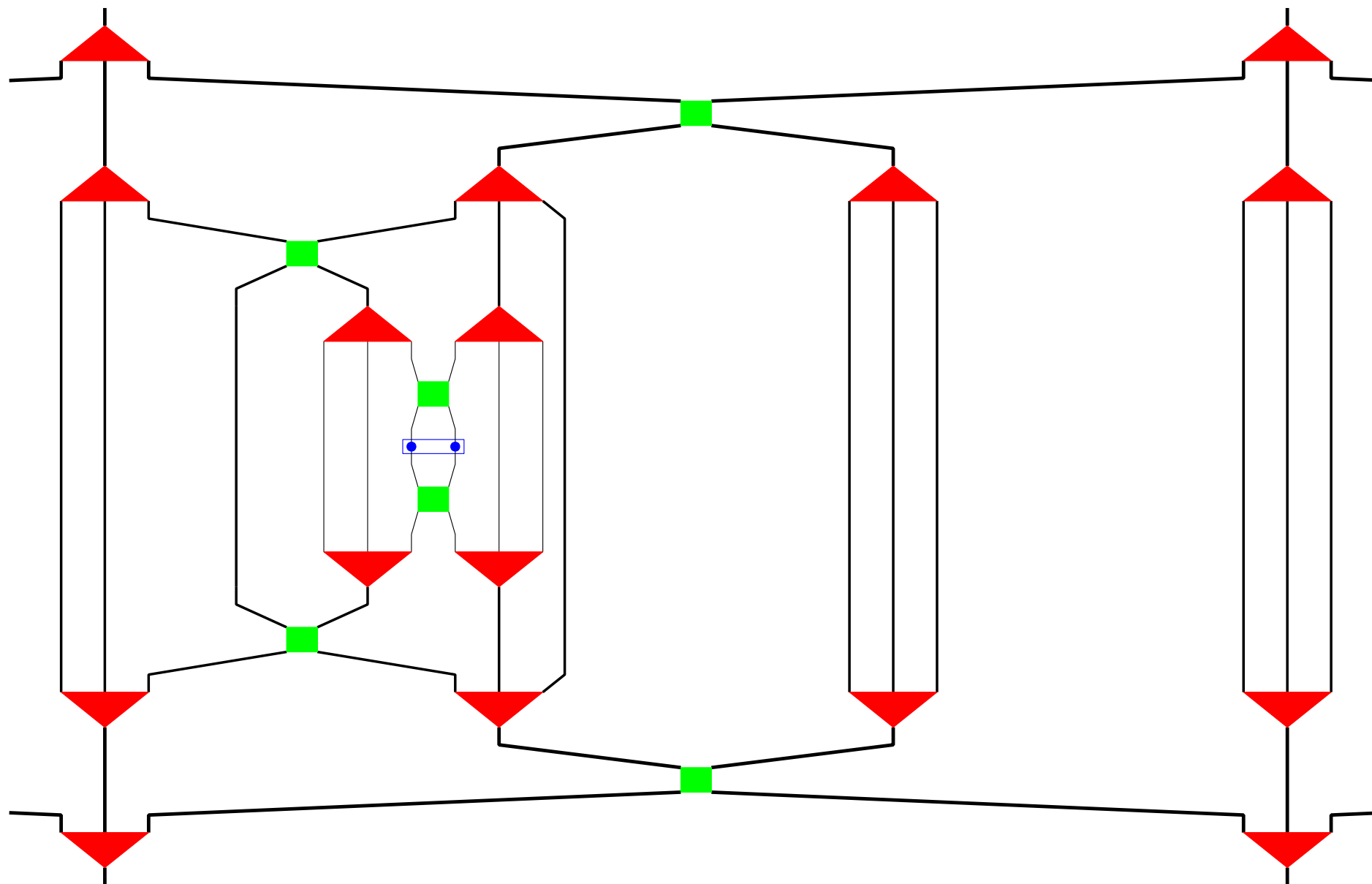
# MERA: expectation value



# MERA: expectation value

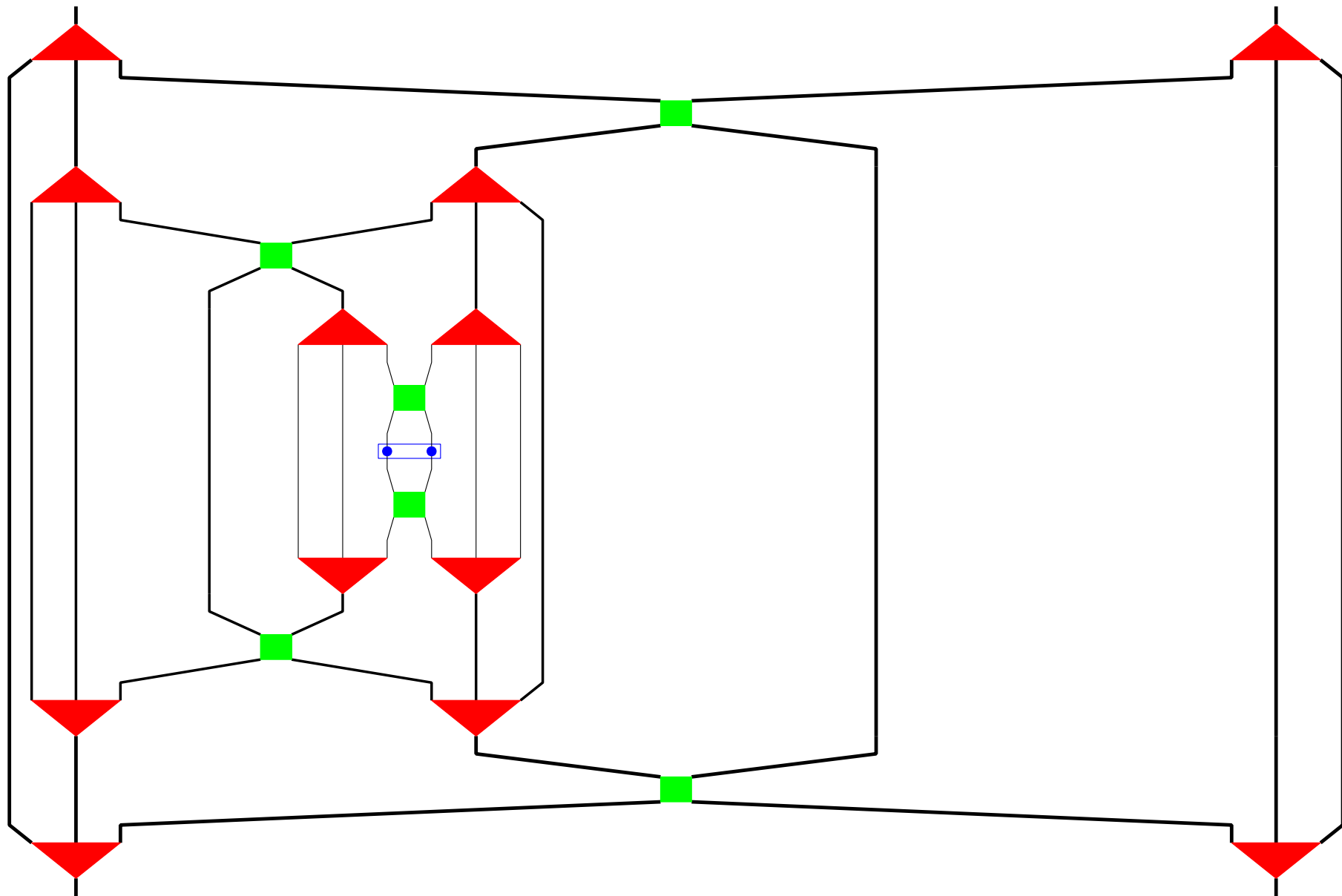


# MERA: expectation value





# MERA: expectation value



# Applications

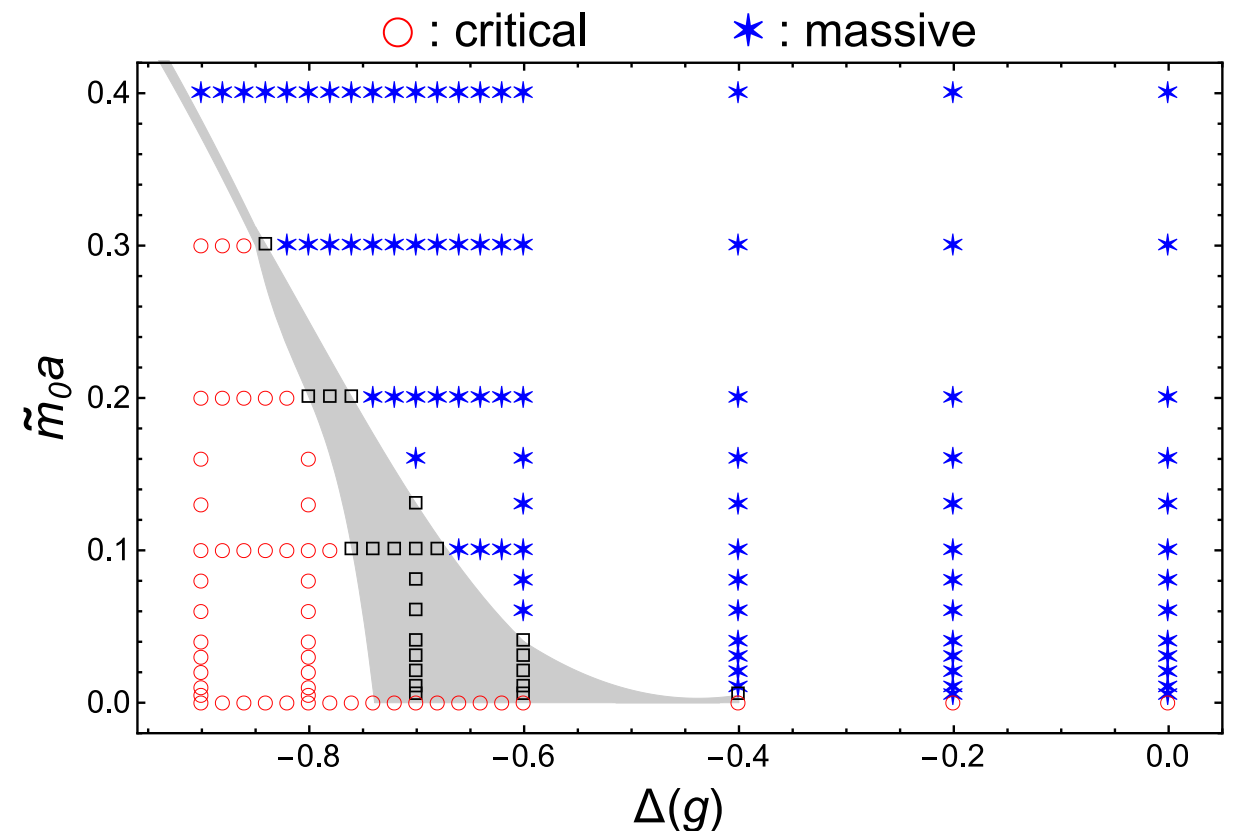
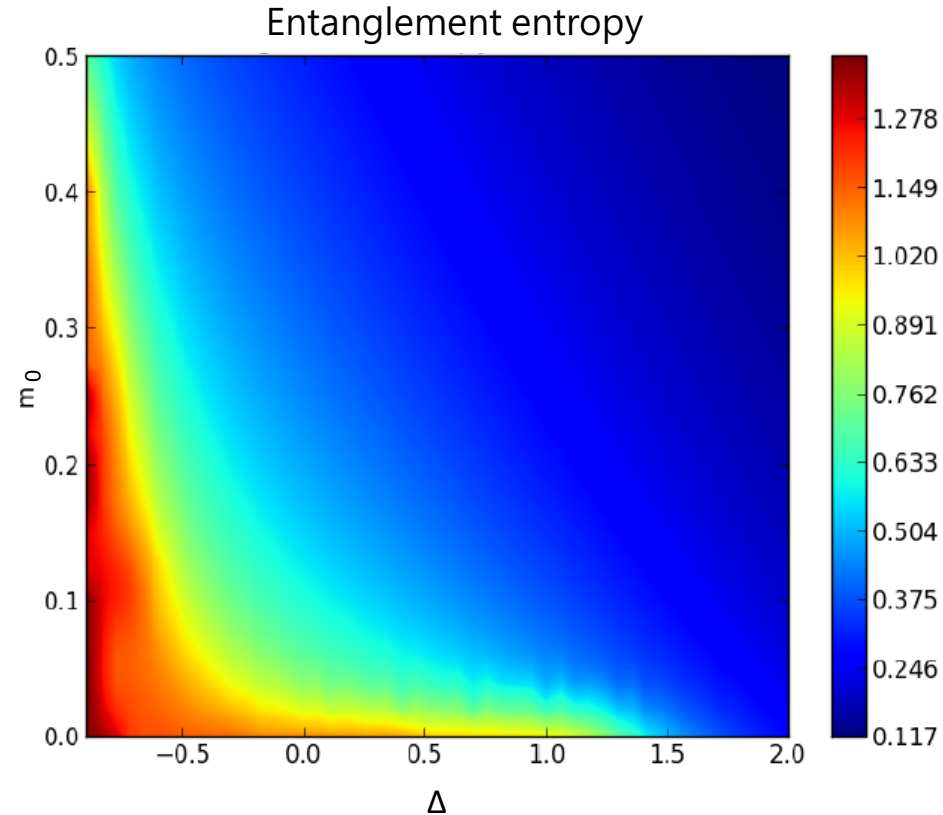
- Quantum Frustrated Magnets (DMRG, iPEPS/iPESS)
- Topological order (DMRG, PESS)
- Disordered system (Tree TN, PEPS)
- Dynamics (Mostly tDMRG/TDVP)
- Open systems (MPS, PEPS)
- Conformal Field Theory (sMERA, iDMRG)
- Classical Statistical Mechanics (PEPS)
- Boundary CFT (bMERA, DMRG+IBC)
- Holography (MERA, other)
- Quantum Field Theory (MPS, PEPS)
- Quantum-classical programming (MPS)
- Machine Learning (MPS, MERA-like)

# Example: (1+1)D Thirring Model

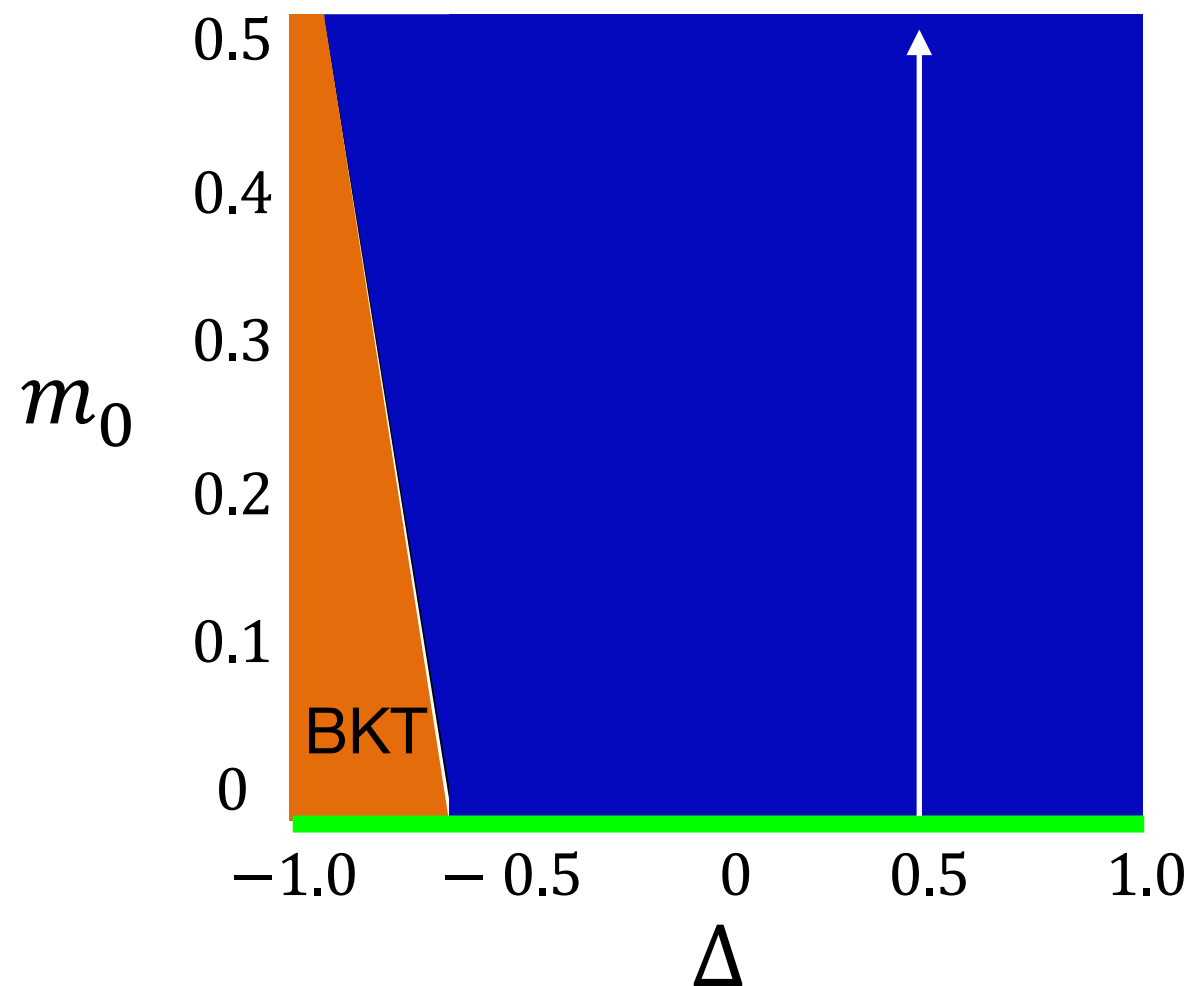
$$S_{\text{Th}}[\psi, \bar{\psi}] = \int d^2x \left[ \bar{\psi} i \gamma^\mu \partial_\mu \psi - m_0 \bar{\psi} \psi - \frac{g}{2} \left( \bar{\psi} \gamma_\mu \psi \right)^2 \right]$$

$$\bar{H}_{\text{XXZ}} = \nu(g) \left[ -\frac{1}{2} \sum_n^{N-2} \left( S_n^+ S_{n+1}^- + S_{n+1}^+ S_n^- \right) + a \tilde{m}_0 \sum_n^{N-1} (-1)^n \left( S_n^z + \frac{1}{2} \right) + \Delta(g) \sum_n^{N-1} \left( S_n^z + \frac{1}{2} \right) \left( S_{n+1}^z + \frac{1}{2} \right) \right]$$

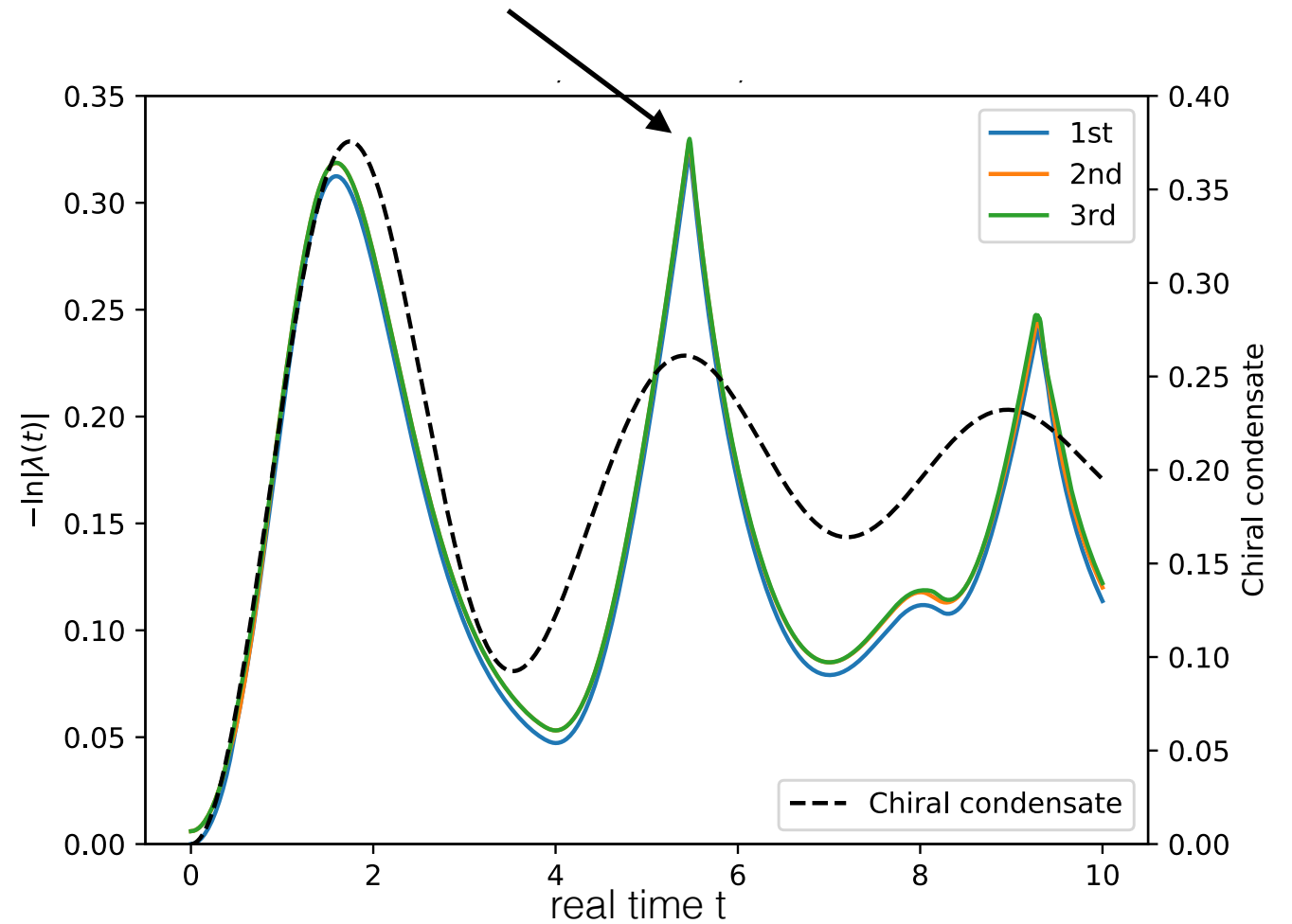
$$\nu(g) = \frac{2\gamma}{\pi \sin(\gamma)}, \tilde{m}_0 = \frac{m_0}{\nu(g)}, \Delta(g) = \cos(\gamma), \text{ with } \gamma = \frac{\pi - g}{2}$$



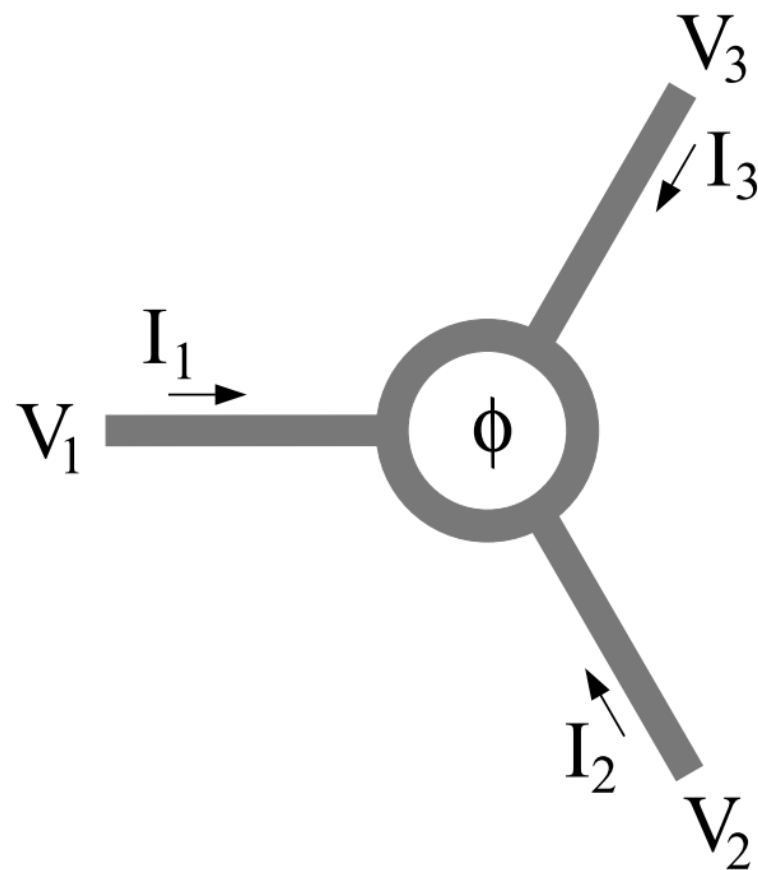
# Example: (1+1)D Thirring Model



## Dynamical phase transition



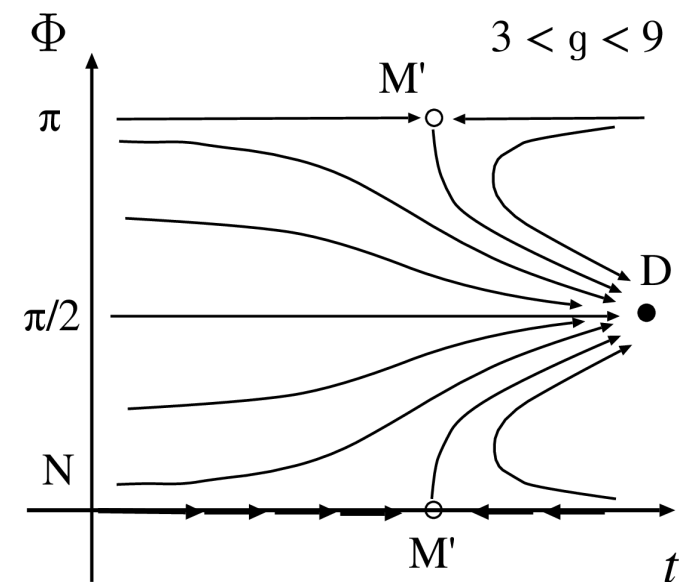
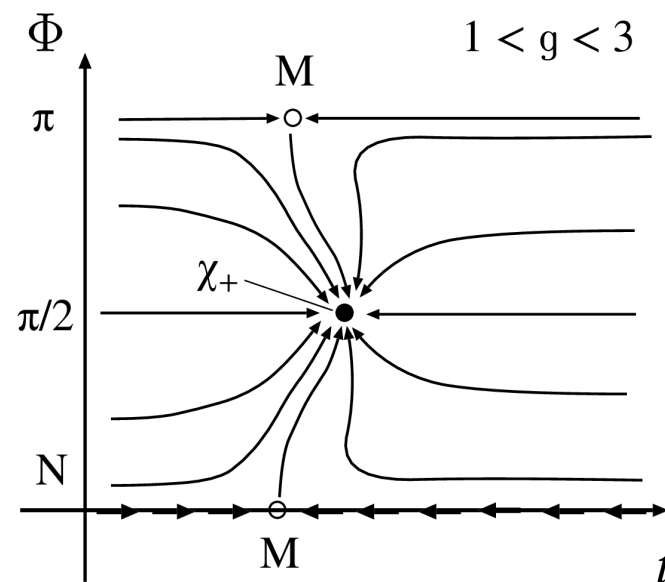
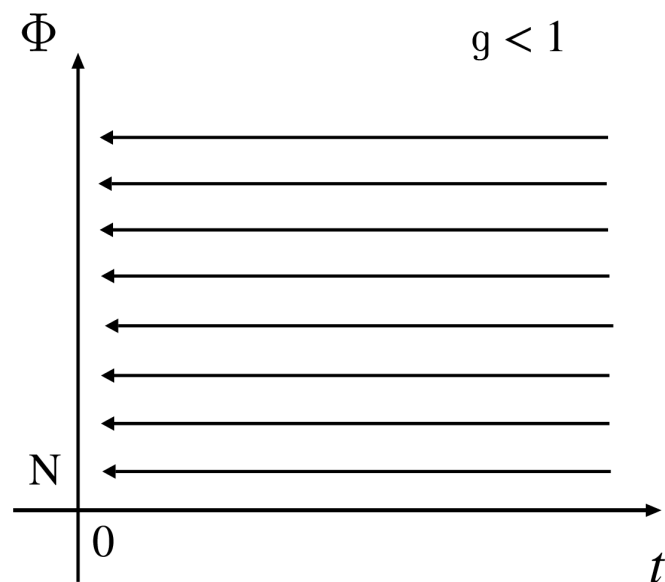
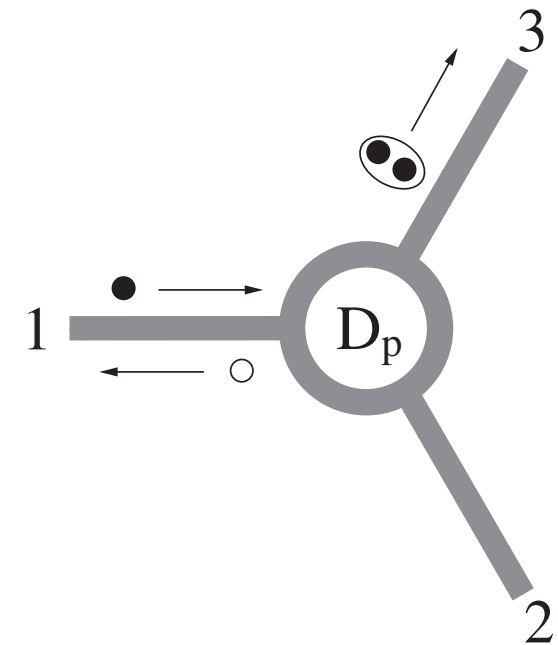
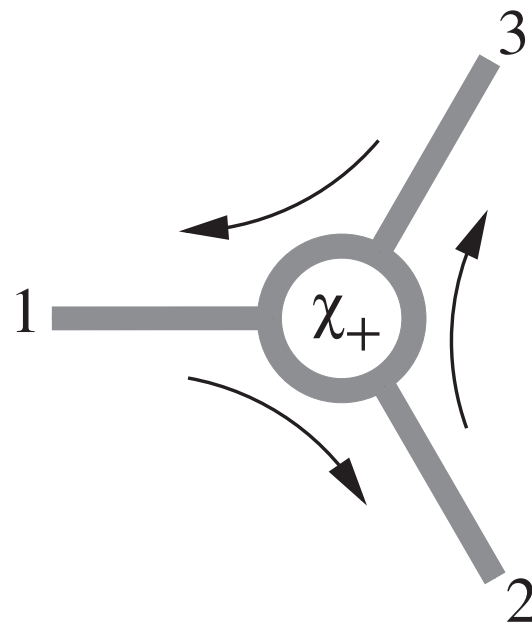
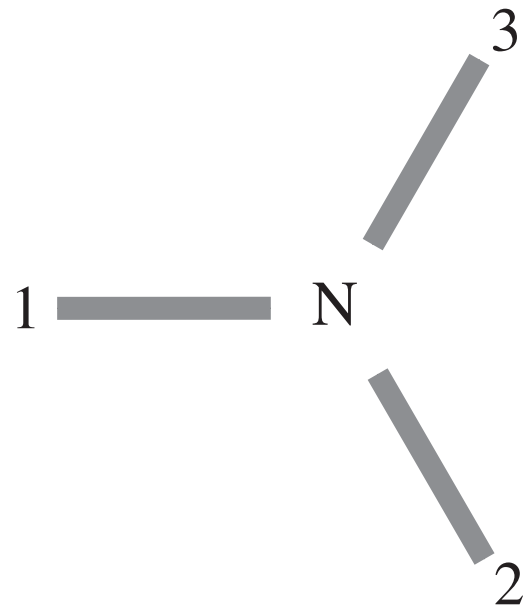
# Example: Y-junction of TLL wires



- Y-junction of interacting quantum wires: Tomonaga-Luttinger Liquid wires
- RG fixed point determined by the interaction in the wires and flux in the junction
- DMRG+Infinite BC

Oshikawa et al. J. Stat. Mech. (2006) P02008

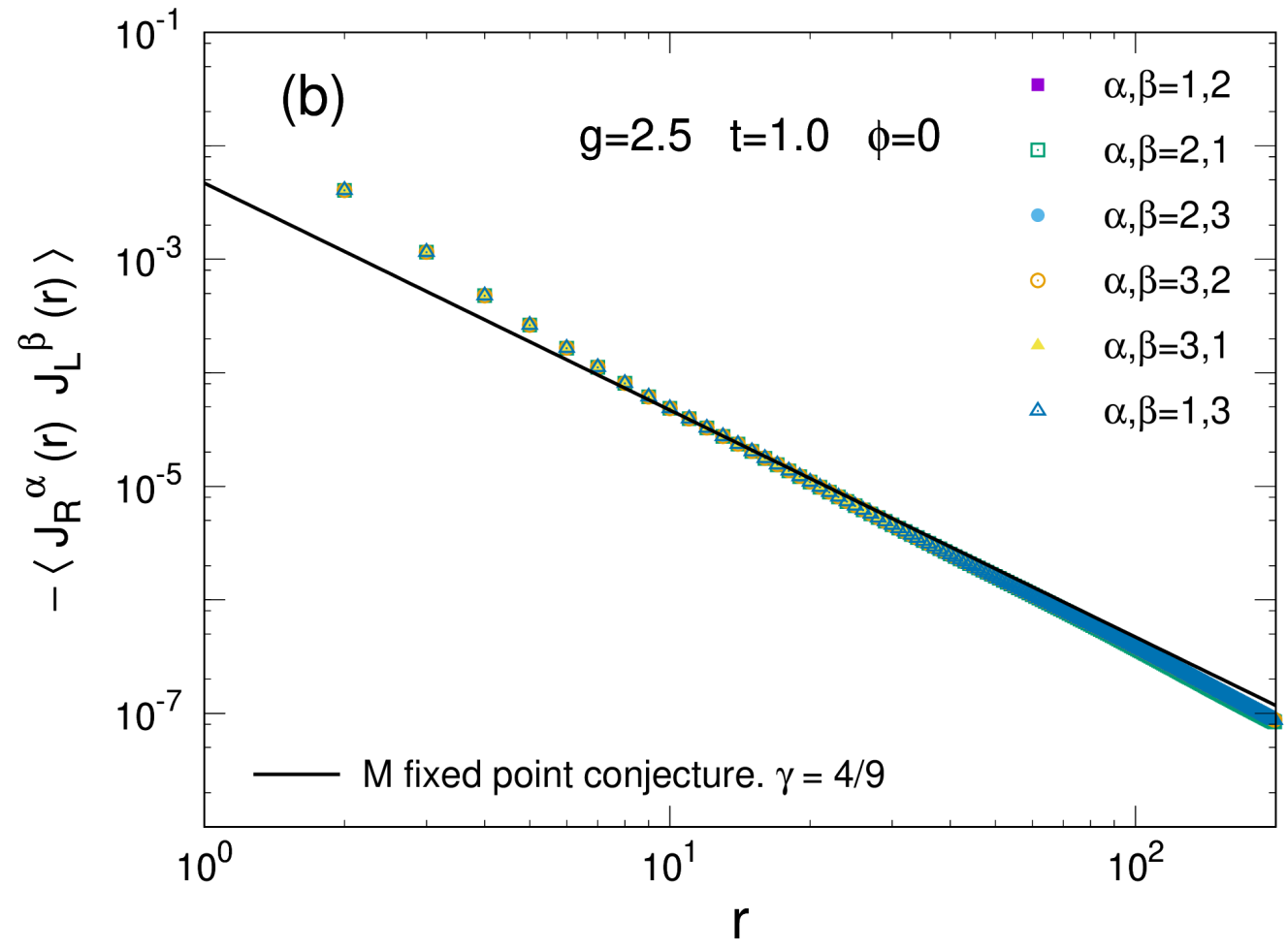
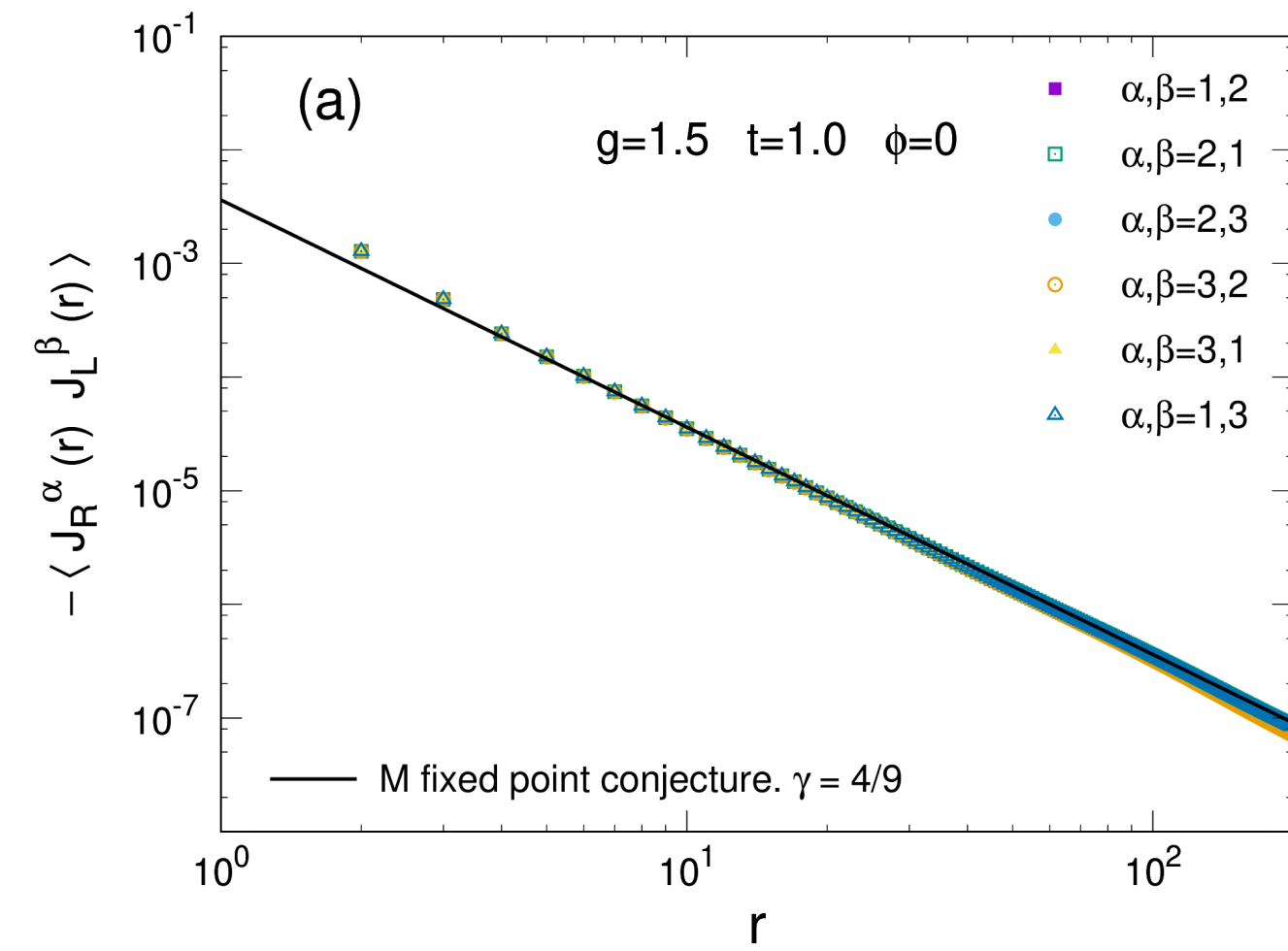
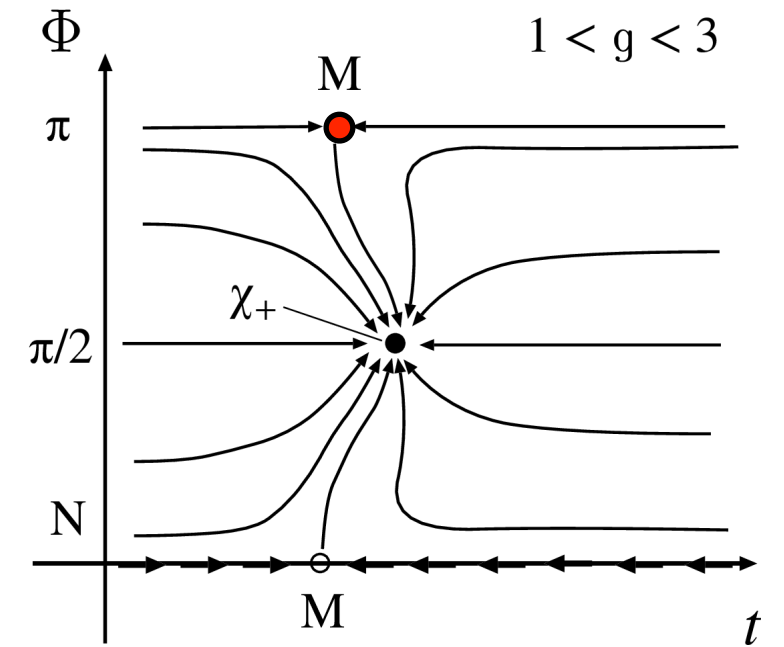
# RG Fixed Points



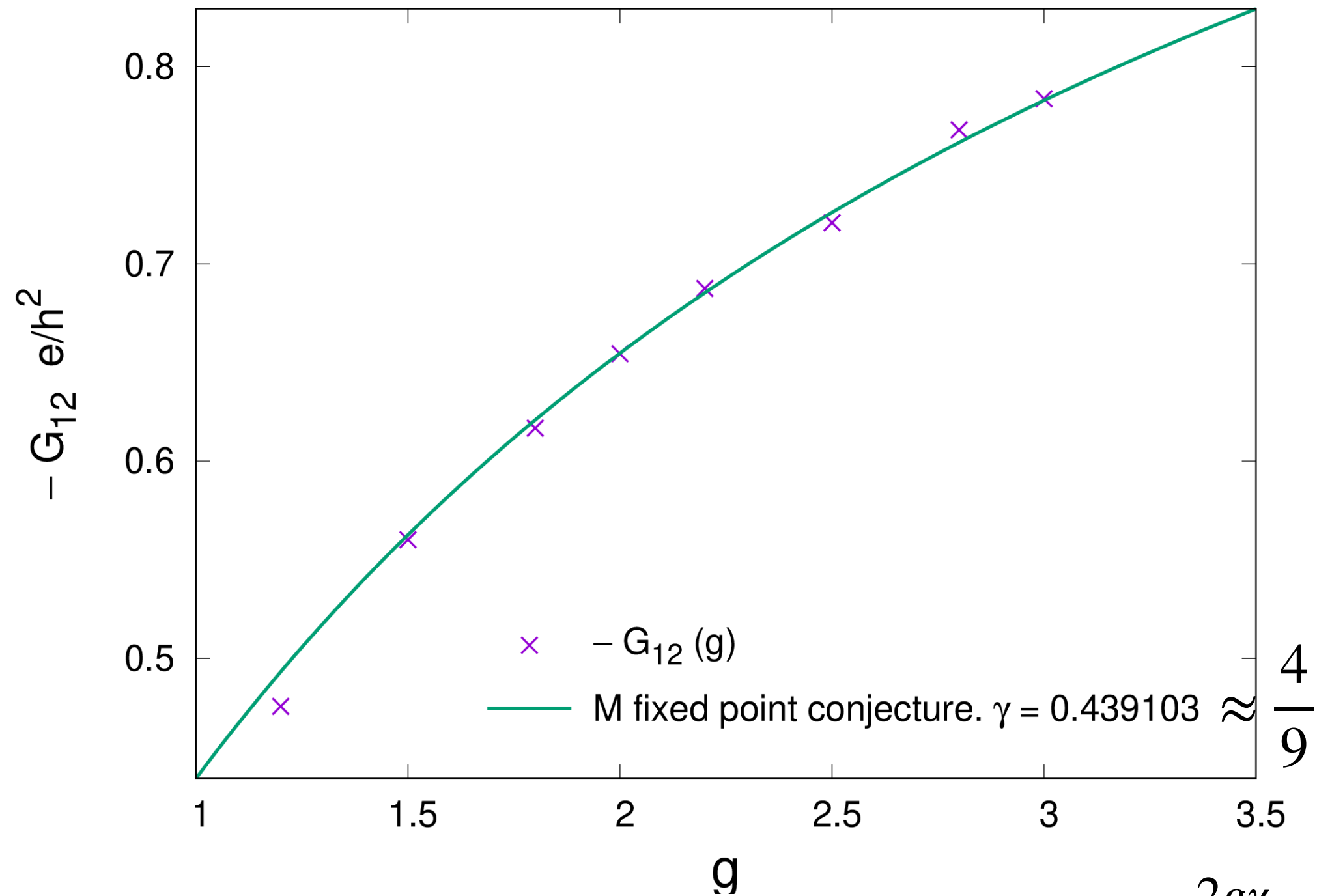
# $1 < g < 3$ : M Fixed Point

- Time-reversal symmetric unstable fixed point

$$G_{\alpha\beta}^M = \frac{2g\gamma}{2g + 3\gamma - 3g\gamma} \frac{e^2}{h}, \gamma = \frac{4}{9}$$



# $1 < g < 3$ : M Fixed Point



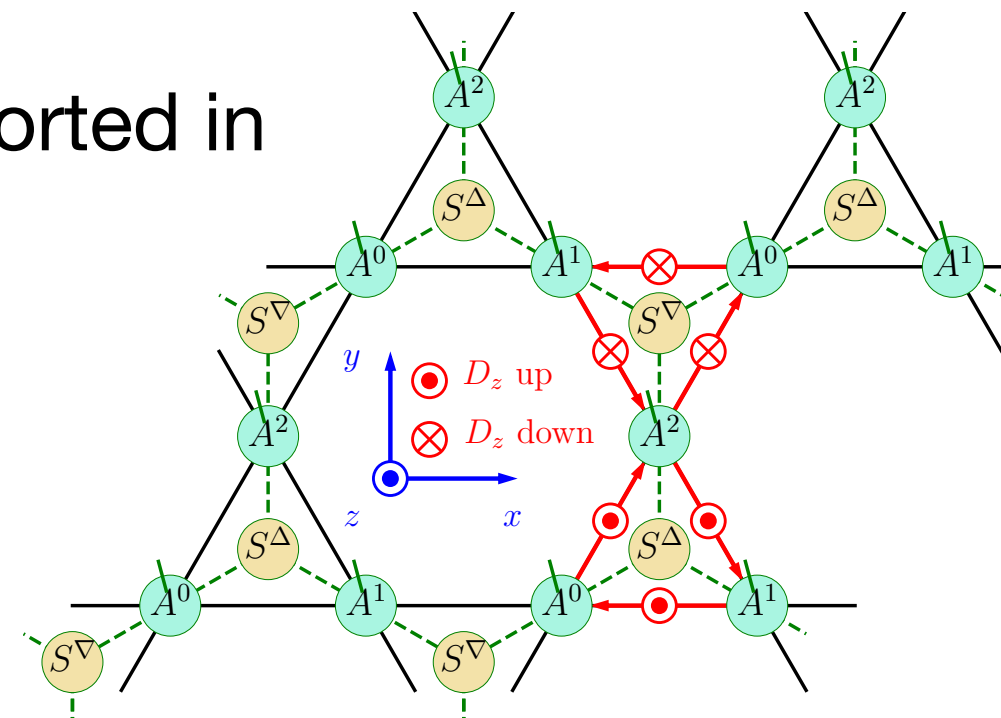
$$G_{\alpha\beta}^M = \frac{2g\gamma}{2g + 3\gamma - 3g\gamma} \frac{e^2}{h}, \gamma = \frac{4}{9}$$



# Example: Kagome AFM+ DM interaction

$$H = \sum_{\langle i,j \rangle} \mathbf{S}_i \cdot \mathbf{S}_j + D \hat{z} \cdot (\mathbf{S}_i \times \mathbf{S}_j)$$

- Kagome AF Heisenberg model: Gapless spin liquid
- $D_z \approx 0.08J$ ,  $D_{\perp} \approx 0.01J$  in Herbertsmithite
- Infinite Projected-Entangled Symplex State (iPESS)
- $D_c \approx 0.012(2)J$ , spin liquid physics reported in Herbertsmithite needs to be reaccessed

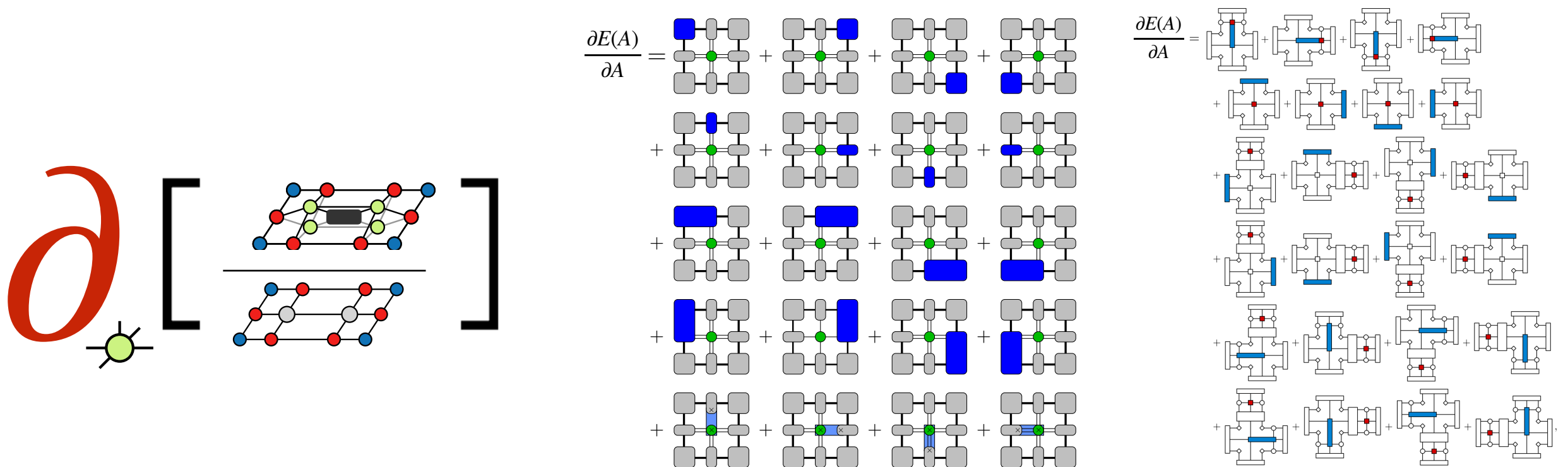


H. J. Liao, et al., Phys. Rev. Lett. 118, 137202 (2017).

C.-Y. Lee, B. Normand, YJK Phys. Rev. B 98, 224414 (2018)

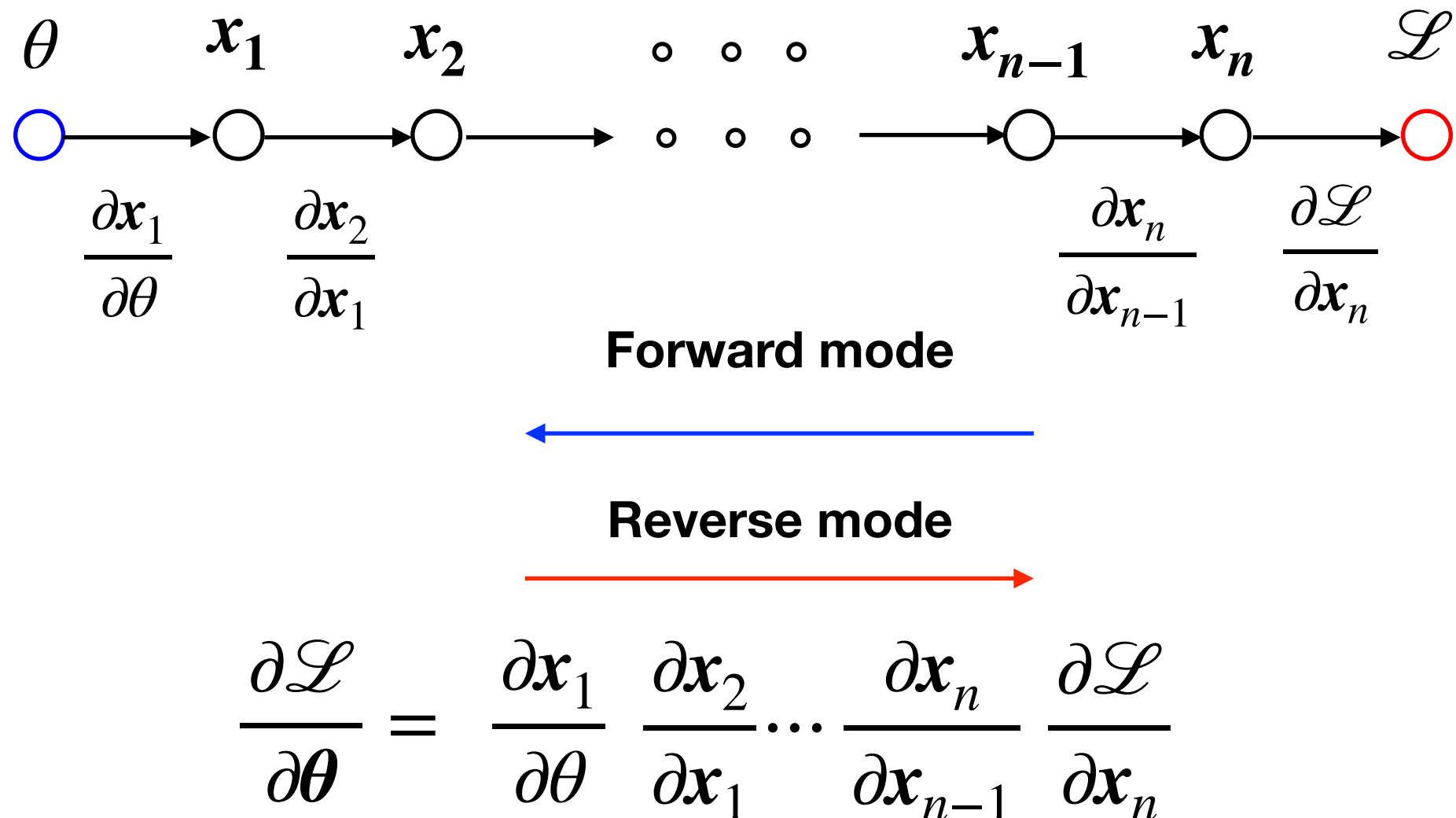
# Outlook: Learn from DL community

- Differentiable Programming



- Automatic differentiation! AutoGrad

# Outlook: Learn from DL community



- Automatic differentiation in DL (Tensorflow, PyTorch, Flux/Zygote)

# Outlook: Bring TN computation to HPC

- Tensor network software
  - ITensor (C++, Julia) Abelian symmetry/GPU
  - mptoolkit (C++) non-Abelian symmetry/GPU
  - TeNPy (Python) Abelian symmetry
  - uni10 (C++/Python) Abelian symmetry/GPU (v3 work in progress)
  - TNSPackage (Fortran 2003)
  - TensorKit.jl (Julia) non-Abelian symmetry
  - mptensor (C++/Python) non-symmetric/HPC
  - TensorNetwork (Python+ Tensorflow) non-symmetric/Cloud computing (CPU+GPU+TPU?)
  - Tor10 (python +PyTorch) symmetric/ML frame work (work in progress)
  - TensorNetworkAD.jl (Julia) Tensor Network with AD